Learning Deduction Rules by Induction

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Leaning Logics

- **Given**: a set **S** of formulas and their logical consequences **T**.
- Find: an axiomatic system K that produces T from S.

"Can Machines Learn Logics?"

(C. Sakama & K. Inoue, 8th Int'l Conf. Artificial General Intelligence, Berlin, July 2015; LNAI 9205)



Given input (S, T), a machine **M** produces an axiomatic system **K**.

Challenging Problems

- Can we develop an algorithm **C** for learning a classical or non-classical logic **L**?
- Does a machine M discover a new axiomatic system K such that K |- F iff L|- F for any formula F?



Outline of this study

- We use the LF1T induction algorithm (learning from 1-step transitions) for learning deduction rules of propositional logic.
- We show some experimental results.

LF1T: Learning from 1-step transitions (Inoue, Ribeiro, Sakama, **MLJ** 2014)[†]

- Input: a set E of pairs of (Herbrand) interpretations
- **Output**: a program P s.t. $J = T_P(I)$ for any $(I, J) \in \mathbf{E}$ where
- *P* is a (propositional) definite logic program
- $T_P(I) = \{ a \mid a \leftarrow b_1, \dots, b_n \text{ is in } P \text{ s.t. } \{b_1, \dots, b_n\} \subseteq I \}$
- A rule $a \leftarrow b_1, ..., b_n$ is **consistent** with (I, J) if $\{b_1, ..., b_n\} \subseteq I$ implies $a \in J$

Note: LF1T is introduced for normal logic programs in (+)

Learning Deduction Rules by LF1T

- We assume a deduction system L represented by a **metalogic program** *P* that provides transitions (*I*, *J*) satisfying $J = T_P(I)$.
- Given (*I*, *J*) as an input, our goal is to examine whether LF1T can reproduce correct inference rules of L represented by meta-rules in *P*.



Example

• Given the Herbrand base:

B={ hold(p), hold(q), hold(r), hold(p \rightarrow r) },

a rule with hold(r) in the head is constructed as follows.

• **Step 0**: **LF1T** starts with the most general rule:

hold(r)←

(1)

Step 1: The transition ({},{}) is given. (1) is inconsistent with this (namely, {} should produce {hold(r)} under (1)), so (1) is minimally specialized by introducing an atom from B:

hold(r)←hold(p)	(2)
hold(r)←hold(q)	(3)
hold(r)←hold(r)	(4)
hold(r)←hold(p→r)	(5)

Example

 Step 2: The transition ({hold(p)}, {hold(p)}) is given. $hold(r) \leftarrow hold(p)$ (2) is inconsistent with this, so (2) is specialized into $hold(r) \leftarrow hold(p), hold(q)$ $hold(r) \leftarrow hold(p), hold(r)$ $hold(r) \leftarrow hold(p), hold(p \rightarrow r)$ These rules are respectively subsumed by $hold(r) \leftarrow hold(q)$ (3) $hold(r) \leftarrow hold(r)$ (4) $hold(r) \leftarrow hold(p \rightarrow r)$ (5)hence removed. As a result, (3),(4) and (5) remain.

Example

• **Step 3**: The transition ({hold(q)}, {hold(q)}) is given. $hold(r) \leftarrow hold(q)$ (3)is inconsistent with this, so (3) is specialized into $hold(r) \leftarrow hold(q), hold(p)$ (6) $hold(r) \leftarrow hold(q), hold(r)$ $hold(r) \leftarrow hold(q), hold(p \rightarrow r)$ The last two rules are respectively subsumed by $hold(r) \leftarrow hold(r)$ (4) $hold(r) \leftarrow hold(p \rightarrow r)$ (5)and removed. As a result, (4), (5) and (6) remain.

input	output	
({}, {})	$\begin{array}{ll} hold(r) \leftarrow hold(p) & hold(r) \leftarrow hold(q) \\ hold(r) \leftarrow hold(r) & hold(r) \leftarrow hold(p \rightarrow r) \end{array}$	
({hold(p)},{hold(p)})	<mark>hold(r)←hold(p)</mark> hold(r)←hold(q) hold(r)←hold(r) hold(r)←hold(p→r)	
({hold(q)},{hold(q)})	$\frac{hold(r) \leftarrow hold(q)}{hold(r) \leftarrow hold(p \rightarrow r)} hold(r) \leftarrow hold(p), hold(q)$	
({hold(p→r)},{hold(p→r)})	hold(r)←hold(r) hold(r)←hold(p→r) hold(r) ←hold(p),hold(q) hold(r)←hold(p→r),hold(p) hold(r)←hold(p→r),hold(q)	
({hold(p),hold(q)},{hold(p),hold(q)})	hold(r)←hold(r) hold(r) ←hold(p),hold(q) hold(r)←hold(p→r),hold(p) hold(r)←hold(p→r),hold(q)	
({hold(p→r),hold(q)},{hold(p→r),hold(q)})	hold(r)←hold(r) hold(r)←hold(p→r),hold(p) hold(r)←hold(p→r),hold(q)	
({hold(p→r),hold(p)}, {hold(p),hold(r)})	hold(r)←hold(r) :Repetition hold(r)←hold(p→r),hold(p) :Modus Ponens	

Experimental Results

- Given B={ hold(p), hold(¬p), hold(q), hold(¬q), hold(p→q), hold(q→r), hold(p→r) }, LF1T produces:
 - hold(¬p) ← hold(¬q) \land hold(p \rightarrow q) : **Modus Tollens**
 - − hold(p→r) ← hold(p→q) \land hold(q→r) : Hypothetical Syllogism
- Given B={ hold(p), hold(¬p), hold(q), hold(¬q), hold(p∨q), hold(¬p∨¬q), hold(r∨s), hold(¬r∨¬s), hold(p→r), hold(q→s) }, LF1T produces:
 - − hold(p) ← hold(p∨q) ∧ hold(¬q) : **Disjunctive Syllogism**
 - hold(r∨s) ← hold(p∨q) \land hold(p→r) \land hold(q→s)

: Constructive Dilemma

- hold(¬p∨¬q) ← hold(¬r∨¬s) ∧ hold(p→r) ∧ hold(q→s)

: Destructive Dilemma

• Given a transition (I,J)=({hold($p \rightarrow q$), hold(q)}, {hold(p)}), LF1T produces

- hold(p) ← hold(q) \land hold(p \rightarrow q)

: Fallacy of Affirming the Consequence (a rule for Abduction)

Summary

- Given transitions specifying premises and their consequences, LF1T successfully produces inference rules of natural deduction in propositional logic.
- The method is applied to learning non-deductive inference rules such as abduction.
- A limitation is that the number of possible transitions increases exponentially in proportion to the size of the Herbrand base.