Negotiation by Abduction and Relaxation

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Motivation

- In negotiation dialogues, agents generate proposals by reasoning on their own goals.
- In automated negotiation, behavior of agents is usually represented as specific (meta-)knowledge of an agent, or specified as negotiation protocols in particular problems.
- The goal of this research is to develop general inference rules for producing proposals and to mechanize a process of exchanging (counter-)proposals in negotiation dialogues.

Contributions

- Introduce methods for generating 3 different types of proposals:
 - conditional proposals by abduction
 - neighborhood proposals by relaxation
 - conditional neighborhood proposals by abduction and relaxation
- Develop a negotiation protocol between two agents.
- Provide a procedure for computing proposals.

Problem Setting

- one-to-one negotiation between two agents.
- An agent has a knowledge base represented by an abductive logic program.
- Negotiation proceeds in a series of rounds and each agent makes a proposal at every round.
- An agent that received a proposal responds in two ways: accept/reject the proposal or building a counter-proposal.

Logic Programming (or Answer Set Programming)

A logic program considered here contains disjunction (;), explicit negation (¬), and default negation (not), which are used for representing incomplete information. The meaning of a program is given by answer sets.

Example (A scholar in Hawaii)

```
swimming; shopping \leftarrow \neg study, \neg study \leftarrow not study.
```

The program has two answer sets: { swimming, ¬study} and

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{ swimming, \neg study } and { shopping, \neg study }.
```

Extended Abduction

- An abductive program is a pair <P,H> where P is a logic program and H is a set of literals representing hypotheses (called abducibles).
- Given an observation G as a conjunction L₁, ..., L_m, not L_{m+1}, ..., not L_n, (L_i: literal) a pair (E, F) is an explanation of G if
 1. (P\F) ∪ E has an answer set satisfying G,
 2. (P\F) ∪ E is consistent,
 3. E and F are sets of ground literals s.t.
 E⊆ H\P and F⊆ H∩P.
- A set S is a belief set of <P,H> satisfying G if S is an answer set of (P \ F) ∪ E satisfying 1-3 above.
- An explanation (E, F) is minimal if
 E⊆ E' and F⊆ F' for any explanation (E', F').

Proposal

- A proposal G is a conjunction
 L₁, ..., L_m, not L_{m+1}, ..., not L_n, (L_i: literal)
 where every variable in G is existentially quantified and range-restricted.
- A proposal G is called a critique if G=accept or G=reject.
- A proposal G is accepted in an abductive program <P,H> if P has an answer set satisfying G.

Conditional Proposal by Abduction

Given an abductive program <P,H> and a proposal G, if (E,F) is a minimal explanation of G θ for some substitution θ , the conjunction

 $G\theta$, E, not F

is called a **conditional proposal**, where E, **not** F represents $A_1,...,A_k$, **not** $A_{k+1},...,$ **not** A_l for $E=\{A_1,...,A_k\}$ and $F=\{A_{k+1},...,A_l\}$.

* A conditional proposal represents a minimal requirement for accepting G.

Example

An agent seeks a position of a research assistant at the computer department of a university with the condition that the salary is *at least 50K USD* per year.

Then, he makes his request as

 $G = assist(comp_dept)$, salary(x), $x \ge 50K$.

Exxample

The university has the abductive program <P,H>: P: salary(40K) ← assist(comp_dept), **not** hasPhD, salary(60K) ← assist(comp_dept), hasPhD, salary(50K) ← assist(math_dept), $salary(55K) \leftarrow sys_admin(comp_dept),$ $employee(x) \leftarrow assist(x),$ $employee(x) \leftarrow sys \ admin(x),$ assist(comp_dept); assist(math_dept); sys admin(comp_dept) ←, H: hasPhD.

Exxxample

- First, P has no answer set satisfying G, so G is not accepted as it is.
- Next, (E,F)=({ hasPhD },{ }) becomes the minimal explanation of

```
G \theta =assist(comp_dept), salary(60K) with \theta ={ x / 60K }.
```

Then, the conditional proposal made by the university becomes

assist(comp_dept), salary(60K), hasPhD.

Relaxation

- Relaxation is a technique of cooperative query answering in databases.
- When an original query fails in a DB, relaxation expands the scope of the query by relaxing constraints in the query.
- This allows the DB to return neighborhood answers which are related to the original query.

Methods for Relaxation

Given an abductive program <P,H> and a proposal G, G is relaxed to G' in the following three ways:

- Anti-instantiation: Construct G' s.t. G' θ = G for some substitution θ .
- Dropping conditions: Construct G' s.t. G'⊂G.
- Goal replacement: When G is a conjunction G₁,G₂ and there is a rule L ← G₁' in P
 s.t. G₁' θ =G₁, build G' as L θ,G₂.

Neighborhood Proposals by Relaxtion

- Let G' be a proposal by anti-instantiation or dropping conditions. If P has an answer set satisfying G' θ, G' θ is called a neighborhood proposal by anti-instantiation/dropping conditions.
- Let G' be a proposal by goal replacement.
 For a replaced literal L∈G' and a rule H ← B in P s.t. L=H σ for some substitution σ, put G"=(G'\{L}) ∪ B σ. If P has an answer set satisfying G" θ, G" θ is called a neighborhood proposal by goal replacement.

Example, cont.

Given the initial proposal

```
G = assist(comp\_dept), salary(x), x \ge 50K,
produce
 G_1 = assist(w), salary(x), x \ge 50K
by substituting comp_dept with a variable w.
As G_1\theta_1 = assist(math\_dept), salary(50K)
with \theta_1 = \{ w / math\_dept \} is satisfied by an
  answer set of P, G_1\theta_1 becomes a
  neighborhood proposal by anti-instantiation.
```

Exxample

Given the initial proposal

 $G = assist(comp_dept)$, salary(x), $x \ge 50K$, produce

 $G_2 = assist(comp_dept)$, salary(x),

by dropping the salary condition.

As $G_2 \theta_2 = assist(comp_dept)$, salary(40K)

with $\theta_2 = \{ x / 40K \}$ is satisfied by an answer set of P, $G_2 \theta_2$ becomes a neighborhood proposal by dropping conditions.

Exxxample

Given the initial proposal $G = assist(comp_dept)$, salary(x), $x \ge 50K$, produce G_3 = employee(comp_dept), salary(x), $x \ge 50K$ by replacing assist(comp_dept) with employee(comp_dept) using the rule $employee(x) \leftarrow assist(x)$ in P. By G_3 and the rule $employee(x) \leftarrow sys_admin(x)$ in P, $G_3' = sys_admin(comp_dept)$, salary(x), $x \ge 50K$ is produced. As $G_3'\theta_3 = sys_admin(comp_dept)$, salary(55K) with $\theta_3 = \{ x / 55K \}$ is satisfied by an answer set of P, $G_3\theta_3$ is a neighborhood proposal by goal replacement.

Negotiation Protocol: Overview

- Negotiation starts by a proposal of one agent Ag₁.
- Another agent Ag₂ either accepts it, rejects it, or builds a counter-proposal. In case of acceptance, negotiation ends in success. In case of rejection, Ag₂ informs Ag₁ of a reason for rejection.
- In response to rejection, Ag₁ tries to change its initial proposal. In response to a counter-proposal made by Ag₂, Ag₁ evaluates it.
- The process iterates until negotiation ends in success or failure. A negotiation fails when every counter-proposal made by one agent is rejected by another agent.

Negotiation Protocol: Tips

- Possible (counter-)proposals are accumulated in a negotiation set of each agent at every round.
- Rejected proposals are accumulated in a failed proposal set to avoid proposing once rejected proposals.
- Reasons for rejection of proposals by one agent are accumulated in a critique set of another agent. An agent takes care of its critique set for building new proposals.

Properties

Theorem: Let Ag₁ and Ag₂ be two agents having abductive programs <P₁, H₁> and <P₂, H₂>, respectively.

- If <P₁, H₁> and <P₂, H₂> are function-free (i.e., both P_i and H_i contains no function symbol), every negotiation terminates.
- If a negotiation terminates with agreement on a proposal G, both <P₁, H₁> and <P₂, H₂> have belief sets satisfying G.

Example – Negotiation Dialogue

```
A seller has the abductive program \langle P_s, H_s \rangle:
P_s: pc(b_1, 1G, 512M, 80G); pc(b_2, 1G, 512M, 80G) \leftarrow
              % pc(brand, CPU, Memory, HDD)
      dvd-rw : cd-rw ←.
 normal\_price(1300) \leftarrow pc(b_1, 1G, 512M, 80G), dvd-rw,
normal\_price(1200) \leftarrow pc(b_1, 1G, 512M, 80G), cd-rw,
normal\_price(1200) \leftarrow pc(b_2, 1G, 512M, 80G), dvd-rw,
price(x) \leftarrow normal\_price(x), add\_point(x),
price(x*0.9) \leftarrow normal\_price(x), pay\_cash, not add\_point(x),
add_point ←.
H<sub>s</sub>: add_point, pay_cash.
```

Exxample

A buyer has the abductive program $\langle P_b, H_b \rangle$:

```
P_b: drive \leftarrow dvd-rw,
       drive \leftarrow cd-rw.
       price(x) \leftarrow
       pc(b_1, 1G, 512M, 80G) \leftarrow
       dvd-rw ←,
       cd-rw \leftarrow not dvd-rw,
             % if dvd-rw is not available, buy cd-rw.
       ← pay_cash, % do not pay by cash
     \leftarrow price(x), x > 1200, % price must not exceed 1200
H<sub>b</sub>: dvd-rw
```

Exxxample

```
(1st round) First, the buyer proposes:
  G_{b^1}: pc(b<sub>1</sub>, 1G,512M,80G), dvd-rw, price(x), x≤1200.
P<sub>s</sub> has no answer set satisfying G<sub>b</sub><sup>1</sup>, then the seller
   does not accept it. The seller abduces the minimal
   explanation (E,F)=( { pay_cash }, { add_point } )
  which explains G_{b}^{1} \theta_{1} with \theta_{1} = \{ x/1170 \}.
The seller constructs the conditional proposal:
 G_{s}^{1}: pc(b<sub>1</sub>, 1G,512M,80G), dvd-rw, price(1170),
               pay_cash, not add_point
and offers it to the buyer.
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Exxxxample

(2nd round) The buyer does not accept G_s^1 because she cannot pay it by cash. The buyer returns the critique G_b^2 : reject to the seller.

As no other conditional proposal exists, the seller next produces neighborhood proposals. He relaxes G_b^1 by dropping $x \le 1200$ in the condition and produces

 $pc(b_1, 1G, 512M, 80G), dvd-rw, price(x).$

As P_s has an answer set satisfying

 G_{s^2} : $pc(b_1, 1G, 512M, 80G)$, dvd-rw, price(1300),

the seller offers it as a new proposal.

Exxxxxample

(3rd round) The buyer does not accept G_{s^2} because she cannot pay more than 1200. The buyer again returns the critique

*G_b*³: reject

to the seller.

The seller then considers another proposal by replacing the brand b_1 with a variable w, G_{b_1} now becomes pc(w, 1G, 512M, 80G), dvd-rw, price(x), $x \le 1200$.

As P_s has an answer set satisfying

 G_s^3 : $pc(b_2, 1G, 512M, 80G)$, dvd-rw, price(1200),

the seller offers it as a new proposal.

Exxxxxxample

answer set satisfying it. The buyer then changes her original

(4th round) The buyer does not accept G_{s}^{3} because P_{b} has no

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goal. She relaxes G_{b^1} by goal replacement using the rule
   drive ← dvd-rw in P<sub>b</sub> and produces
    pc(b_1, 1G, 512M, 80G), drive, price(x), x≤1200.
Next, using the rule drive \leftarrow cd-rw in P<sub>b</sub> she produces
    pc(b_1, 1G, 512M, 80G), cd-rw, price(x), x \le 1200.
As the minimal explanation (E,F)=(\{\},\{dvd-rw\}) explains the above,
   the buyer proposes the conditional neighborhood proposal
 G_b^4: pc(b<sub>1</sub>, 1G,512M,80G), cd-rw, not dvd-rw, price(x), x≤1200
to the seller. Since P_s also has an answer set satisfying G_b^4,
the seller accepts it and sends the message G_s^4 =accept to the
```

buyer. Thus, the negotiation ends in success.

Computation

Given a proposal G and an abductive program <P,H>;

- a conditional proposal is computed using extended abduction by computing a minimal explanation of G.
- a **neighborhood proposal** is computed by first building a relaxed/neighborhood goal G' then computing an answer set satisfying $G' \theta$.
- a conditional neighborhood proposal is computed by combining the above two steps.
- These computation is realized on top of the existing answer set solvers.