Representing Argumentation Frameworks in Answer Set Programming

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Transformation from AF to LP representational viewpoint

meta-interpretative representation

individual AFs are given as input to a single metalogic program which produces canonical (or selected) models characterizing input AF semantics.

object-level representation

individual AFs are transformed to corresponding logic programs whose canonical models characterize input AF semantics.

! Encoding AF semantics in meta-interpretative LP often results in complicated programs.

Transformation from AF to LP semantical viewpoint

extension-based semantics

extensions of an AF are characterized by canonical models of a transformed logic program.

labelling-based semantics

labellings of an AF are characterized by canonical models of a transformed logic program.

! Extension-based semantics does not distinguish rejected arguments and undecided arguments.

Transformation from AF to LP transformational viewpoint

one-to-one mapping

different semantics of an AF are characterized by different semantics of a transformed LP.

many-to-one mapping

different semantics of an AF are characterized by a single semantics of a transformed LP.

! Many-to-one mapping enables one to use a single LP solver for computing different semantics of AF.

Transformation from AF to LP Existing Studies

Studies	representation	semantics	transformation
Dung (1995)	meta- interpretative	extension	stable ext. → stable model grounded ext. → well-founded model
Nieves, et al. (2008)	object level	extension	preferred ext. → stable model
Wu, et al. (2009)	object level	labelling	complete labelling → 3-valued stable model
Wakaki, et al. (2009)	meta- interpretative	labelling	complete/stable/grounded/preferred/ semi-stable labelling → ASP
Egly, et al. (2010)	meta- interpretative	extension	complete/stable/grounded/preferred/ ext. → ASP
Caminada, et al. (2015)	object level	labelling	stable/grounded/preferred/semi-stable labelling → stable/well-founded/ regular/L-stable model
Our current study	object level	labelling	complete/stable/grounded/preferred/ labelling → ASP

Preliminaries

- An argumentation framework: AF = (Ar, att).
- For $x \in Ar$, $x = \{ y \mid (y, x) \in att \}$.
- Labelling L: $Ar \rightarrow \{in, out, und\}$
- When L(a)=in (resp. out or und) for $a \in Ar$, it is written as in(a) (resp. out(a) or und(a)) (called labelled arguments).
- Complete labelling, stable labelling, grounded labelling, and preferred labelling are defined as usual.
- A logic program consists of rules:

```
a_1 \vee \cdots \vee a_l \leftarrow a_{l+1}, \dots, a_m, \text{ not } a_{m+1}, \dots, \text{not } a_n
```

where a_i : ground atom, **not**: negation as failure

 The semantics of a program is given by stable models (or answer sets).

LP Rules for AF

- Given AF=(Ar,att), the **Herbrand base** B is defined as $B=\{in(x), out(x), und(x) \mid x \in Ar \}$.
- The set Γ_{AF} of rules is defined as follows:

```
\Gamma_{AF} = \{ in(x) \leftarrow out(y_1), ..., out(y_k) \mid x \in Ar \text{ and } x^- = \{y_1, ..., y_k\} \text{ (k} \ge 0) \}
\cup \{ out(x) \leftarrow in(y) \mid (y, x) \in att \}
\cup \{ \leftarrow in(x), \text{ not } out(y) \mid (y, x) \in att \}
\cup \{ \leftarrow out(x), \text{ not } in(y_1), ..., \text{not } in(y_k) \mid x \in Ar \text{ and } x^- = \{y_1, ..., y_k\} \text{ (k} \ge 0) \}
```

AF program under complete semantics

Given AF = (Ar, att), an **AF-program under the complete** semantics Π^{C}_{AF} is defined as follows:

```
\Pi^{\mathsf{C}}_{AF} = \Gamma_{AF} \cup \{ in(x) \lor out(x) \lor und(x) \leftarrow | x \in Ar \} 
\cup \{ \leftarrow in(x), out(x) | x \in Ar \} 
\cup \{ \leftarrow in(x), und(x) | x \in Ar \} 
\cup \{ \leftarrow out(x), und(x) | x \in Ar \}
```

Theorem

The sets of labelled arguments under the complete semantics of AF coincide with the stable models of $\Pi^{\rm C}_{AF}$



• Given $AF = (\{a,b,c\}, \{(a,b),(b,a),(b,c)\})$, Π^{C}_{AF} consists of $in(a) \leftarrow out(b)$, $in(b) \leftarrow out(a)$, $in(c) \leftarrow out(b)$, $out(a) \leftarrow in(b)$, $out(b) \leftarrow in(a)$, $out(c) \leftarrow in(b)$, $\leftarrow in(a)$, not out(b), $\leftarrow in(b)$, not out(a), $\leftarrow in(c)$, not out(b), $\leftarrow out(a)$, not in(b), $\leftarrow out(b)$, not in(a), $\leftarrow out(c)$, not in(b), in(x) v out(x) v und(x) \leftarrow $where <math>x \in \{a,b,c\}$ $\leftarrow in(x), out(x)$, $\leftarrow in(x), und(x)$, $\leftarrow out(x), und(x)$ where $x \in \{a,b,c\}$

• Π^{c}_{AF} has 3 stable models: $\{in(a),out(b),in(c)\},\{out(a),in(b),out(c)\},\{und(a),und(b),und(c)\}$ which are equivalent to 3 sets of labelled arguments under the complete semantics of AF.

AF program under stable semantics

Given AF=(Ar,att), an **AF-program under the stable** semantics Π^{S}_{AF} is defined as follows:

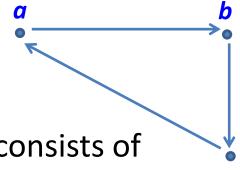
$$\Pi^{S}_{AF} = \Gamma_{AF} \cup \{ in(x) \lor out(x) \leftarrow | x \in Ar \}$$
$$\cup \{ \leftarrow in(x), out(x) | x \in Ar \}$$

Theorem

The sets of labelled arguments under the stable semantics of AF coincide with the stable models of Π^{S}_{AF} .

Corollary

AF has no stable labelling iff Π_{AF}^{S} has no stable model.



• Given $AF = (\{a,b,c\}, \{(a,b), (b,c), (c,a)\}), \Pi^{S}_{AF}$ consists of

```
in(a) \leftarrow out(c), in(b) \leftarrow out(a), in(c) \leftarrow out(b),

out(a) \leftarrow in(c), out(b) \leftarrow in(a), out(c) \leftarrow in(b),

\leftarrow in(a), not out(c), \leftarrow in(b), not out(a), \leftarrow in(c), not out(b),

\leftarrow out(a), not in(c), \leftarrow out(b), not in(a), \leftarrow out(c), not in(b),

in(x) \lor out(x) \leftarrow  where x \in \{a,b,c\}

\leftarrow in(x), out(x)  where x \in \{a,b,c\}
```

• Π^{s}_{AF} has no stable model, so AF has no stable labelling.

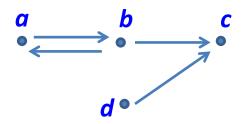
AF program under grounded semantics

Given AF=(Ar,att), an **AF-program under the grounded** semantics Π^{G}_{AF} is defined as follows:

$$\Pi^{G}_{AF} = \Gamma_{AF} \cup \{ und(x) \leftarrow \mathbf{not} \ in(x), \ \mathbf{not} \ out(x) \mid x \in Ar \}$$

Theorem

The set of labelled arguments under the grounded semantics of AF coincides with the stable model of $\Pi^{\rm G}_{AF}$.



• Given $AF = (\{a,b,c,d\}, \{(a,b),(b,a),(b,c),(d,c)\}), \Pi^G_{AF}$ consists of $in(a) \leftarrow out(b), in(b) \leftarrow out(a), in(c) \leftarrow out(b), out(d), in(d) \leftarrow,$ $out(a) \leftarrow in(b), out(b) \leftarrow in(a), out(c) \leftarrow in(b), out(c) \leftarrow in(d),$ $\leftarrow in(a), not out(b), \leftarrow in(b), not out(a), \leftarrow in(c), not out(b),$ $\leftarrow in(c), not out(d), \leftarrow out(a), not in(b), \leftarrow out(b), not in(a),$ $\leftarrow out(c), not in(b), not in(d), \leftarrow out(d),$ $und(x) \leftarrow not in(x), not out(x) \text{ where } x \in \{a,b,c,d\}$

• Π^{G}_{AF} has the unique stable model $\{und(a), und(b), out(c), in(d)\}$ which is equivalent to the set of labelled arguments under the grounded semantics of AF.

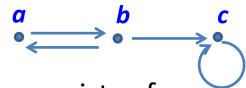
AF program under preferred semantics

- Given AF=(Ar,att), the **Herbrand base** B' is defined as $B'=\{in(x), out(x), IN(x), OUT(x), UND(x) \mid x \in Ar\}$.
- Given AF=(Ar,att), an **AF-program under the preferred** semantics Π^{P}_{AF} is defined as follows:

```
\Pi^{\mathsf{P}}_{AF} = \Gamma_{AF} \cup \{ in(x) \lor out(x) \leftarrow | x \in Ar \} 
\cup \{ IN(x) \leftarrow in(x), \mathbf{not} \ out(x) \mid x \in Ar \} 
\cup \{ OUT(x) \leftarrow \mathbf{not} \ in(x), out(x) \mid x \in Ar \} 
\cup \{ UND(x) \leftarrow in(x), out(x) \mid x \in Ar \}
```

Theorem

There is a 1-1 correspondence between the sets of labelled arguments under the preferred semantics of AF and the stable models of $\Pi^{\rm P}_{AF}$.



• Given $AF = (\{a,b,c\}, \{(a,b),(b,a),(b,c),(c,c)\})$, Π^P_{AF} consists of $in(a) \leftarrow out(b)$, $in(b) \leftarrow out(a)$, $in(c) \leftarrow out(b)$, out(c), $out(a) \leftarrow in(b)$, $out(b) \leftarrow in(a)$, $out(c) \leftarrow in(b)$, $out(c) \leftarrow in(c)$, $\leftarrow in(a)$, $not \ out(b)$, $\leftarrow in(b)$, $not \ out(a)$, $\leftarrow in(c)$, $not \ out(b)$, $\leftarrow in(c)$, $not \ out(c)$, $\leftarrow out(a)$, $not \ in(b)$, $\leftarrow out(b)$, $not \ in(a)$, $\leftarrow out(c)$, $not \ in(b)$, $not \ in(c)$, $in(x) \ v \ out(x) \leftarrow where \ x \in \{a,b,c\}$ $IN(x) \leftarrow in(x)$, $not \ out(x)$, $OUT(x) \leftarrow not \ in(x)$, out(x), $UND(x) \leftarrow in(x)$, out(x) where $x \in \{a,b,c\}$

Π^P_{AF} has 2 stable models
 { out(a), in(b), out(c), OUT(a), IN(b), OUT(c) }
 { in(a), out(b), in(c), out(c), IN(a), OUT(b), UND(c) }

Then 2 sets $\{OUT(a), IN(b), OUT(c)\}$ and $\{IN(a), OUT(b), UND(c)\}$ correspond to 2 sets of labelled arguments under the preferred semantics of AF (of which the 1st one represents stable labelling).

Application: Query Answering

Theorem Let AF = (Ar, att). For any $x \subseteq Ar$,

- 1. x is labelled in in some complete labelling of AF iff $\Pi^{c}_{AF} \cup \{\leftarrow not in(x)\}$ has a stable model.
- 2. x is labelled in in every complete labelling of AF iff $\Pi^{c}_{AF} \cup \{\leftarrow in(x)\}$ has no stable model.

The result also holds by replacing *in* with *out* or *und*.

Similar results hold for $\Pi^{\rm S}_{AF_{,}}\Pi^{\rm G}_{AF_{,}}$ and $\Pi^{\rm P}_{AF}$.

Application: Enforcement

- The universal argumentation framework (UAF) is (U, att_U) where U is the set of all arguments in the language and $att_U \subseteq U \times U$.
- AF=(Ar, att) is defined as a sub-AF of the UAF s.t. $Ar \subseteq U$ and $att = att_U \cap (Ar \times Ar)$.
- B_U is defined as $B_U = \{ in(x), out(x), und(x) \mid x \in U \}$.
- Given an **enforcement set** $E \subseteq B_U$, if one can construct a new AF' such that (i) AF' = (Ar', att') where $Ar \subseteq Ar' \subseteq U$ and $att' = att_U \cap (Ar' \times Ar')$, and (ii) AF' has a complete labelling L s.t. $L(x) = \emptyset$ for any $\emptyset(x) \subseteq E$, then AF **satisfies** the enforcement E (under the complete semantics).

Application: Enforcement

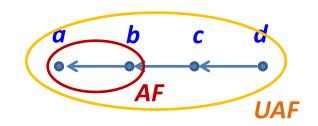
• An AF-program under the complete semantics for the enforcement $\varepsilon\Pi^{C}_{AF}$ is defined as

$$\varepsilon\Pi^{\mathsf{C}}_{AF} = \Pi^{\mathsf{C}}_{UAF} \setminus \{ in(x) \leftarrow, \leftarrow out(x) \mid x \in U \setminus Ar \}$$

Theorem Given an enforcement set $E \subseteq B_U$, AF = (Ar, att) satisfies the enforcement E iff

 $\varepsilon\Pi^{c}_{AF} \cup \{\leftarrow \text{not } \ell(x) \mid \ell(x) \in E \text{ where } \ell \in \{in, out, und}\}\}$ has a stable model.

Similar results hold for $\Pi^{\rm S}_{AF_{,}}\Pi^{\rm G}_{AF_{,}}$ and $\Pi^{\rm P}_{AF}$.



• Let $UAF = (\{a,b,c,d\},\{(d,c),(c,b),(b,a)\})$ and $AF = (\{a,b\},\{(b,a)\})$. Then AF has the complete labelling $\{out(a),in(b)\}$. $\varepsilon\Pi^{C}_{AF}$ consists of

```
in(a) \leftarrow out(b), in(b) \leftarrow out(c), in(c) \leftarrow out(c), \frac{in(d) \leftarrow}{out(a) \leftarrow in(b), out(b) \leftarrow in(c), out(c) \leftarrow in(d),}
ext{out}(a) \leftarrow in(b), in(b) \leftarrow out(c), in(c), out(c) \leftarrow in(d),
ext{out}(a), not out(b), out(b), not out(c), in(c), not out(d),}
ext{out}(a), not out(b), out(c), in(c), cout(c), not out(d),}
ext{out}(a), not out(b), cout(b), not out(c), cout(c), not out(d),}
ext{out}(a), in(c) \leftarrow out(b), not out(c), cout(c), not out(d),}
ext{out}(a), in(c) \leftarrow out(d), in(c) \leftarrow out(d),
ext{out}(a), out(a), cout(a), out(a), cout(a), out(a), cout(a), out(a), cout(a),}
ext{out}(a), in(c) \leftarrow out(c), in(c) \leftarrow out(d),
ext{out}(a), in(c) \leftarrow out(d),
ex
```

• Given $E=\{in(a)\}$, $\varepsilon\Pi^{c}_{AF} \cup \{\leftarrow not \ in(a)\}\$ has the stable model $\{in(a), out(b), in(c), out(d)\}\$. Then AF satisfies the enforcement E, i.e., to enforce in(a), AF is modified by introducing the new argument c and the attack relation (c,b).

Application: Agreement

- Let AF_1 and AF_2 be two sub-AFs of the UAF. If AF_1 (resp. AF_2) has a set S (resp. T) of labelled arguments under a complete labelling such that $S \cap T \neq \{\}$, then AF_1 and AF_2 can reach an **agreement**.
- Let $@\Pi^{c}_{AF}$ be a program in which predicates *in*, *out* and *und* in Π^{c}_{AF} are renamed by *in'*, *out'* and *und'*, respectively. Define

```
\Phi = \{ agree(x) \leftarrow in(x), in'(x) \mid x \in U \}
\cup \{ agree(x) \leftarrow out(x), out'(x) \mid x \in U \}
\cup \{ agree(x) \leftarrow und(x), und'(x) \mid x \in U \}
\cup \{ ok \leftarrow agree(x) \mid x \in U \} \cup \{ \leftarrow not ok \}
```

<u>Theorem</u> AF_1 and AF_2 can reach an agreement iff $\Pi^c_{AF_1} \cup \odot \Pi^c_{AF_2} \cup \Phi$ has a stable model M. In this case, AF_1 and AF_2 agree on each argument x s.t. $agree(x) \in M$.

- † Similar results hold for Π_{AF}^{S} , Π_{AF}^{G} and Π_{AF}^{P} .
- ++ The result is extended to agreement among more than 2 agents.

Final Remark

- Π^{c}_{AF} and Π^{s}_{AF} can be represented by semantically equivalent **normal logic programs**, while Π^{P}_{AF} cannot.
- Thus, Π^{P}_{AF} is in the class of LPs that are more expressive and computationally expensive than others.
- The proposed method is **simple** and **uniform** for different AF semantics.
- Several techniques developed in LP (e.g. equivalence issue, optimisation, update, etc) are directly applied to transformed AF-programs.
- The result of this study implicates potential use of rich LP techniques in AF (via AF-programs).